

# 연습문제 해답

(기초회로이론-개정2판)

2019. 3.

- 최윤식 저 -

## 일반 독자들께

본 교재를 사용해 주셔서 감사 드립니다. 개정2판에는 많은 문제들을 보완 했고, 이전 판에서의 오탈자들을 수정하였습니다.

하지만, 그럼에도 불구하고 이번에도 개정2판의 해답집을 만들면서 보니 또 많은 오류가 있었습니다. 제가 발견한 오류들은 정리하여 올려놓습니다만, 공부하시다가 또 다른 오류를 발견하시면 번거로우시겠지만 연락주시면 감사하겠습니다. 지적해주시는 오류들은 다음 번 수정판에 반영하여 수정하도록 하겠습니다.

본 해답은, 풀이 없이 답만 올려놓았습니다. 풀이와 답은 강사님들께만 제공하여 학생들에게 선택적으로 제공하는 것으로 출판사와 방침을 정했지만, 혼자 공부하시는 분들께서 공부에 도움이 되도록 답만이라도 공개해 달라는 요청이 많아 답만은 제공하는 것으로 방침을 바꾸었습니다.

참고하시고 공부하시는 데에 활용해 주시면 감사하겠습니다. 언제라도 교재에 대한 의견이나 요청이 있으시면 저나 한빛아카데미 출판사에 연락주십시오.

감사합니다.

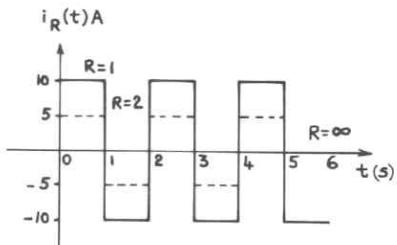
2019. 3. 최윤식 씀

오탈자와 본문 오류 등은 한빛미디어 홈페이지 <http://www.hanb.co.kr> 에서 확인하실 수 있습니다.

편집자 드림

## 제2장 전기회로소자 및 계수

2-1



2-2

- (a)  $E(1) = 2[J]$  (b)  $E(2) = 4[J]$  (c)  $E(3) = 8[J]$  (d)  $E(4) = 10[J]$  (e)  $E(5) = 12[J]$

2-3

- 1)  $v = -250[V]$
- 2)  $v = +100[V]$
- 3)  $v = 200[V]$

2-4

- a)  $P = 18[W]$
- b)  $P = -20[W]$
- c)  $P = -21[W]$

2-5

$$E(0,5) = 3.75[J]$$

2-6

- 1) 구간  $[0,1]$ 에서,  $E[0,1] = \frac{1}{30}[J]$
- 2) 구간  $[0,2]$ 에서,  $E[0,2] = \frac{4}{30}[J]$
- 3) 구간  $[0,5]$ 에서,  $E[0,5] = \frac{11}{30}[J]$

2-7

저항  $R_1$ 에 의하여 소모되는 전력은  $P_1 = 400[W]$ ,  
저항  $R_2$ 에 의하여 소모되는 전력은  $P_2 = 500[W]$ .

2-8

$R = 25\Omega$  이 되고, 100V 전원에 연결하면,  $400[W]$  을 소모한다.

2-9

$v$  는 10V.  $i = -3A$ .

2-10

$0 \leq t \leq 4s$  구간에서, 전력  $P = 80t [W]$

$4 \leq t \leq 5s$  구간에서, 전력  $P = -60t^2 + 320t [W]$

$5 \leq t \leq 10s$  구간에서, 전력  $P = -20t + 200 [W]$

전체 에너지는  $1110[J]$

2-11

(a)  $150[Wh]$

(b) 15원

2-12

$4\Omega$  저항에 의하여 소비된 전력은  $36W$ ,  $8\Omega$  저항에 의하여 소비된 전력은  $32W$ ,  $9\Omega$  저항에 의한 소비전력은  $81W$ .

### 제3장 저항회로

3-1

(a) 1메시, 2노드 (b) 2메시, 4노드 (c) 3메시, 4노드

3-2

(a)  $V_{DE} = 1[V]$  일 때,

$V_{AC} = 8[V]$ ,  $V_{AD} = 3[V]$ , 또한  $V_{AE} = 4[V]$ ,  $V_{AF} = 0[V]$ .

(b)  $V_{CD} = 1[V]$  일 때,

$V_{AC} = 1[V]$ ,  $V_{AD} = 3[V]$ ,  $V_{AE} = -2[V]$ ,  $V_{AF} = -6[V]$

(c)  $V_{FE} = 4[V]$  일 때,

$V_{AD} = 3[V]$ , 나머지는 모름.

3-3

(a)  $i_{AC} = 23mA$ ,  $i_{BD} = 16mA$

(b)  $i_{AC} = 23mA$ .  $i_{BD} = 62mA$

3-4

$R_{eq} = 10\Omega$

3-5

$$i_x = \frac{10}{7} [A]$$

3-6

$$i_s = 6A, v = 45[V]$$

3-7

$$v_1 = 30[V], v = 225[V]$$

3-8

$$R = 3.2\Omega$$

3-9

$$v_0 = \frac{115}{8} i_0$$

3-10

$$v_x = -20V$$

3-11

$$v_0 = 3.2[V]$$

3-12

(a)  $R = 6\Omega$

(b)  $v = 6V, i = 1A$

(c)  $i_2 = \frac{4}{5}A$

3-13

$$2\Omega \text{에 흐르는 전류 } I_2 = \frac{51}{5}A$$

3-14

(a)  $v_{2K\Omega} = 4V, v_{3K\Omega} = 6V, v_{7K\Omega} = 14V$

(b)  $p_{6V\text{전원}} = -12mW, p_{2K\Omega} = 8mW, p_{3K\Omega} = 12mW,$   
 $p_{18V\text{전원}} = -36mW, p_{7K\Omega} = 28mW$

3-15

(a)  $2mV$  저항전류,  $i = 4mA, 3mV$  저항전류  $i = 6mA, 7mV$  저항전류  $i = 14mA$

(b)  $p_{2mV} = 8mW, p_{6mA\text{전원}} = -12mW, p_{3mV} = 12mW, p_{18mA\text{전원}} = 36mW, p_{7mV} = 28mW$

3-16

$3\Omega$ 에 흐르는 전류  $2A$ , 걸리는 전압  $v = 6V$ , 전력  $P = 12W$ .

3-17

임의의 전류 전원 값  $i = 0.12A$ .

3-18

$10\Omega$  소비 전력  $P = 4.096W$ .

3-19

(a)  $100\Omega$  저항 소비 전력  $P = 1600W$

(b)  $300V$  전원  $P = -1200W$  을 소비.

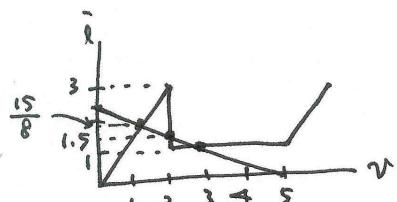
(c)  $P = -640W$  을 소비한다.

3-20

(a) 전류전원에 의하여 공급되는 전력은  $P = 3.6W$ ,

(b)  $900\Omega$ 에 의하여 소비되는 전력은  $P = 1.44W$

3-21



3개의 포인트,  $i = \frac{15}{8}, \frac{3}{2}, 1$  的 값이 가능.

3-22

$v_x = 0.3[V]$ , 종속전원에서 발생하는 전력은  $P = 7.8[W]$

## 제4장 저항회로의 해석방법

4-1

$$i_x = 1A$$

4-2

$$i_x = 0.5A$$

4-3

$$V_A = 0[V] \quad V_B = -2.5[V] \quad V_C = 2.5[V]$$

4-4

$$i(t) = \frac{40}{3}[A]$$

4-5

$$i_A = \frac{11}{3}mA, \quad i_B = 4mA, \quad i_C = -\frac{1}{3}mA$$

4-6

$$R = 7\Omega$$

4-7

$$i_1 = 1.69[A], i_2 = 1.39[A], i_3 = 1.92[A]$$

4-8

$v_1 = 1V$ , 종속전원을  $500\Omega$ 으로 바꾸면,  $v_1 = 1V$

4-9

$$v_x = 6[V]$$

4-10

$$i_x = -0.3A$$

4-11

$$i_B = -1.333[mA], \quad i_C = -3[mA], \quad i_A = 4.333[mA]$$

4-12

$v = 10V$ ,  $i = 0.02A$ , 소비전력은  $P = 0.2W$

4-13

$R = 1\Omega$ 에 의하여 소비되는 전력  $P = \frac{9}{169}[W]$

4-14

$$P = -423W$$

4-15

$$P = 104.3[W] \text{ 혹은 } P = -104.3[W]$$

4-16

$$P = 95.2 \text{ W}$$

4-17

$$P = 0.75 \text{ W}, A = 0.015$$

4-18

독립방정식의 수는 다음의 7개.

$$\text{메시 } 1 : v_1 - v_2 = v_{R_1} + v_{R_7} + v_{L_1}$$

$$\text{메시 } 2 : v_2 = v_{C_3} + v_{R_4} + v_{L_2}$$

$$\text{메시 } 3 : -v_3 = v_{R_6} + v_{R_8} - v_{R_7}$$

$$\text{메시 } 4 : 0 = v_{R_5} - v_{R_8} - v_{L_2}$$

$$\text{메시 } 5 : -v_1 + v_3 = v_{C_1} - v_{R_2} - v_{R_1} - v_{R_6}$$

$$\text{메시 } 6 : -v_4 = v_{C_2} - v_{R_5}$$

$$\text{메시 } 7 : v_4 = v_{R_3} - v_{C_1} - v_{C_2} - v_{R_4}$$

4-19

$$P = 0.8071[\text{W}]$$

## 제5장 회로해석 정리

5-1

$$v_a = 7[\text{V}]$$

5-2

$$v_0 = 30 \text{ V}$$

5-3

4Ω에 흐르는 전류는 2A, 방향은 오른쪽에서 왼쪽으로 흐른다.

5-4

$$v = -3[\text{V}]$$

5-5

테브닌등가회로의  $v_{oc} = -12[\text{V}], R_{th} = 16[\Omega]$ .

5-6

$$R_{th} = 4[K\Omega], \quad v_{oc} = 24[V]$$

5-7

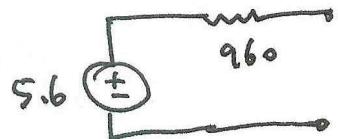
$$R_{th} = 5\Omega, \quad v_{oc} = 18V$$

5-8

$$v_{oc} = 8V, \quad R_{th} = \frac{4}{3}\Omega$$

5-9

$$v_{oc} = 5.6V, \quad R_{th} = 960[\Omega]$$

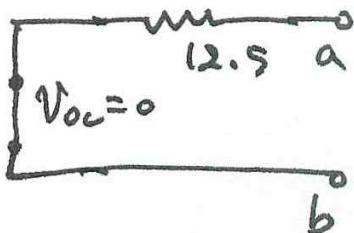


5-10

$$(a) \quad v_{oc} = v = 15[V]. \quad R_{th} = 12.5\Omega$$

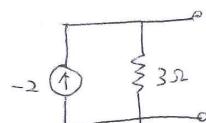


$$(b) \quad R_{th} = 12.5\Omega$$

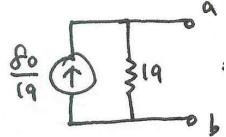


5-11

$$I_{sc} = -2 \quad R_t = 3\Omega \quad \text{노턴등가회로는}$$



5-12



5-13

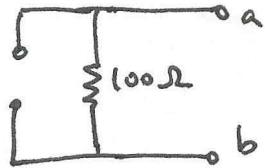
$$i_{sc} = 4A, R_{th} = \frac{v_{oc}}{i_{sc}} = -9\Omega$$

5-14

$$P_{max} = \frac{15}{452} W$$

5-15

(a)  $I_{sc} = 0, R_{th} = 100\Omega$ . 노턴 등가회로는



(b)  $R_L = 100\Omega$

(c) 최대 전달 전력  $P_{max} = 2500[W]$

5-16

(a)  $v_x = 2.8[V]$

(b) 5A 전원전력 14W.

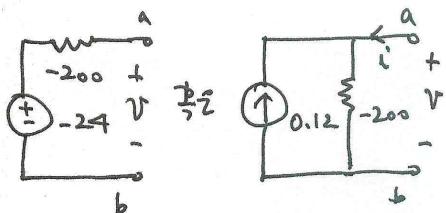
(c) 6V 전원 발생 전력  $p = 21.6 W$

(d) 전력  $p = -12.32[W]$

5-17

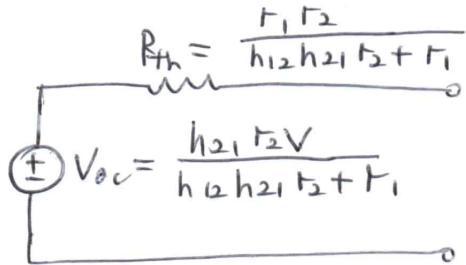
$$v_{oc} = -24[V], R_{th} = -200[\Omega]$$

$$i = -\frac{v}{200} = 0.12$$



5-18

$$R_{th} = \frac{r_1 r_2}{r_1 + r_2 h_{21} h_{12}}. \text{ 테브닌등가회로는}$$



## 제6장 연산증폭기

6-1

$$v = 7[V], \quad i = 0.25[mA]$$

6-2

$$R_1 = 33.3K\Omega, \quad R_2 = 66.6K\Omega, \quad R_3 = 50K\Omega$$

6-3

$$v_o = -1[V]$$

6-4

$$v_a = -10[V], \quad v_b = -6[V], \quad v_c = -6[V]. \quad v_d = -6, \quad v_e = -4, \quad v_g = -4, \quad v_f = \frac{-16}{3}$$

6-5

$$v_x = 4[V], \quad i_a = -0.6[mA]$$

6-6

$$(a) \quad v_{out} = -\frac{R_f}{R_1}w - \frac{R_f}{R_2}x + \frac{(R_2' / R_f')(R_f + (R_1 / R_2))}{(R_1' + (R_2' / R_f'))(R_1 / R_2)}y + \frac{(R_1' / R_f')(R_f + (R_1 / R_2))}{(R_2' + (R_1' / R_f'))(R_1 / R_2)}z$$

$$(b) \quad v_{out} = 10[V]$$

6-7

$$R_f = R_f' = 100K\Omega \text{ 으로 정하면, } R_1 = 25K\Omega, \quad R_2 = 50K\Omega, \\ R_1' = 10K\Omega, \quad R_2' = 100K\Omega$$

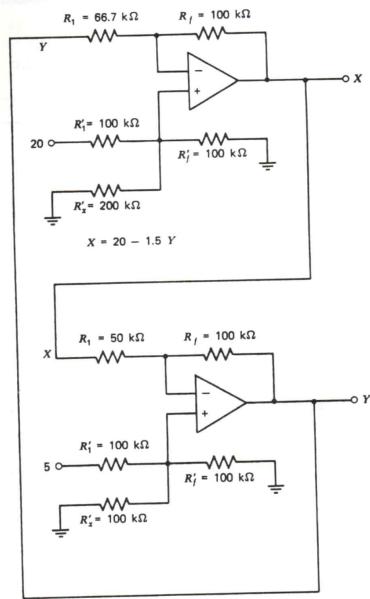
6-8

$$\frac{v_o}{v_s} = \frac{1}{R_3}(R_3 + R_4) + \frac{R_2}{R_3}$$

6-9

$$a = \frac{1}{4}, b = -\frac{3}{4}$$

6-10



## 제7장 에너지 저장소자

7-1

$$v_L(t) = 10^{-3} \frac{d}{dt} (0.1 \sin 10^6 t) = 100 \cos 10^6 t$$

7-2

(a)  $L = 10 [H]$

(b)  $C = 160 [\mu F]$

7-3

(a)  $i(t) = 0.5 \cos t + 0.125 \sin 2t$

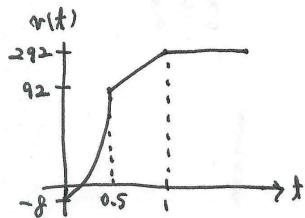
(b)  $E = 0.623 [J]$

7-4

$$0 < t < 0.5 \text{ 때}, v(t) = 400t^2 - 8$$

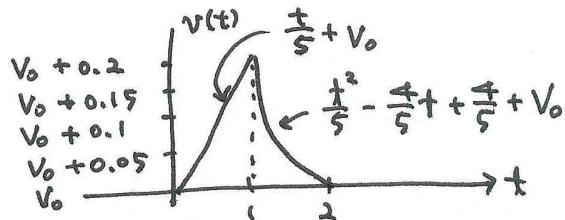
$$0.5 \leq t < 1 \text{ 때}, v(t) = 400t - 108$$

$$t \geq 1 \text{ 때}, v(t) = 292$$



7-5

$$v(t) = \begin{cases} \frac{t}{5} + v_0, & 0 \leq t < 1 \\ \frac{t^2}{5} - \frac{4}{5}t + \frac{4}{5} + v_0, & 1 \leq t < 2 \\ v_0, & 2 \leq t < \infty \end{cases}$$



7-6

$$(a) t=0 \text{에서}, i = 2\pi \times 10^{-5} [A]$$

$$(b) t = \frac{1}{4} \text{ 초에서}, i = 0 [A]$$

$$(c) t = \frac{1}{2} \text{ 초에서}, i = -2\pi \times 10^{-5} [A]$$

7-7

$$t = 300\mu s \text{ 때}, i(300\mu) \approx 0.15 [mA]$$

7-8

$$i_{avg} = 10.42 \times 10^{-3} A$$

7-9

$$(a) i = 3.274e^{\frac{t}{50}} [A]$$

$$2) i = 0.149e^{\frac{t}{50}} [A]$$

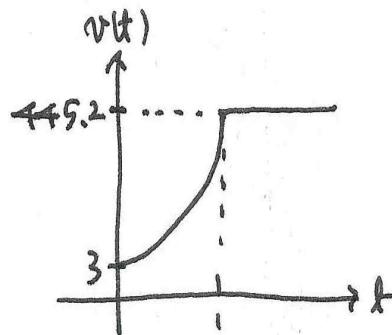
7-10

- (a)  $V = 0.6 [V]$   
 (b)  $V = 0.2e^{-10^4 t}$   
 (c)  $t=0$ 에서  $|V|=0.08 [V]$

7-11

$$0 < t \leq 1 \text{ 때}, v(t) = 3e^{5t}$$

$$t > 1 \text{ 때}, v(t) \approx 445.2$$



$$(a) P(0.2) = 66.50 [W]$$

$$(b) P(0.8) = 26.8 [KW]$$

7-12

- (a)  $E(0) = 2 \times 10^{-9} [J]$   
 (b)  $E(1.571\mu) = 2 \times 10^{-9} [J]$   
 (c) 전체 에너지는  $E = E_L + E_C = 2 \times 10^{-9} [J]$

7-13

$$i_1(0) = 0, i_2(0) = 3, i_3(0) = -2$$

7-14

$$0 < t < \frac{1}{2} \text{ 때}, i_L(t) = 2t - 2,$$

$$\frac{1}{2} \leq t < 1 \text{ 때}, i_L(t) = -1$$

$$1 \leq t < \frac{3}{2} \text{ 때}, i_L(t) = 2t - 3$$

$\frac{3}{2} \leq t < 2$  때,  $i_L(t) = 0$ , 계속하여 각 구간별로 구하면, 최종  $i_L(t)$ 의 파형은

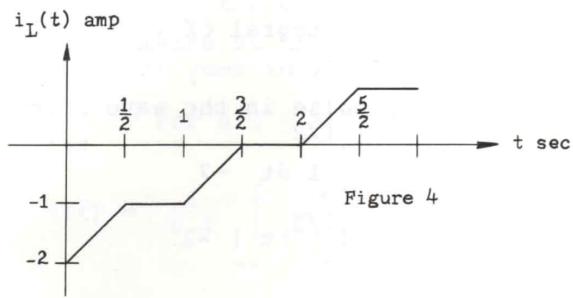


Figure 4

7-15

$$(a) \quad t < 0 \text{ 일 때}, \quad i_1(0^+) = 4[A], \quad i_2(0^+) = 1[A]$$

$$(b) \quad t > 0 \text{ 때}, \quad i(t) = 5e^{-5t}$$

## 제8장 RL과 RC 회로의 완전응답

8-1

$$(a) \quad t = 0^+ \text{에서} \quad i_L(0^+) = 0$$

$$(b) \quad t = \infty \text{에서} \quad i_L(\infty) = 8[A],$$

$$(c) \quad t = 4\text{m초} \text{에서}, \quad i_L(4m) = 5.057[A]$$

8-2

$$p_R = 71.44[W], \quad p_L = 79.76[W], \quad p_S = -151.2[W]$$

8-3

$$\text{1차 미분방정식은 } \frac{di}{dt} = \frac{2}{3}, \quad i(t) = \frac{2}{3}t + 2$$

8-4

$$v(t) = 6 + 2e^{-\frac{4}{3}t}$$

8-5

$$i(t) = -0.04e^{-30t} + 0.06[A]$$

8-6

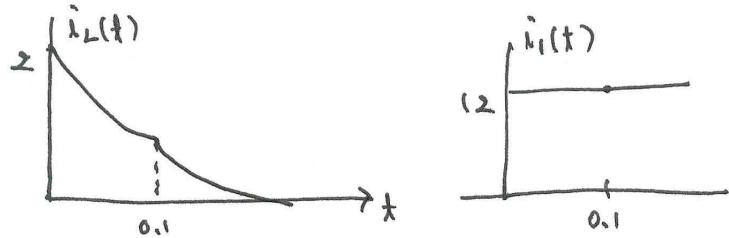
$$v_c(t) = -5e^{-2t} + 5\sqrt{2} \cos(2t - 45^\circ)$$

8-7

$$v(t) = -0.15e^{-\frac{1}{0.38}t} - 0.25$$

8-8

$$i_L(t) \approx 1.21e^{-3(t-0.1)}, i_1(t) = 12[A]$$



8-9

$$i_L(t) = 4e^{-0.5t} - 2$$

8-10

$$(a) i_L(t) = 4 - 4e^{-100t}u(t)[A]$$

$$(b) i_1(t) = 2 - \frac{8}{3}e^{-100t}u(t)[A]$$

8-11

$$i = (0.1 + 0.2e^{-2500t})u(t)[mA]$$

8-12

$$i_L(t) = 0.02(1 - e^{-25000t})u(t)[A]$$

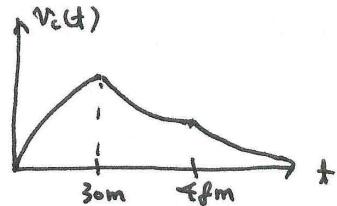
8-13

$$(a) t < 0 \text{ 때}, v_c(0) = 0$$

$$0 \leq t < 30m \text{ 때}, v_c(t) = -10e^{-200t} + 10$$

$$30m \leq t < 48m \text{ 때}, v_c(t) = 4024.2e^{-200t}$$

$$t \geq 48m \text{ 때}, v_c(t) = 33.17e^{-100t}$$



$$(b) v_c(100m) \approx 0.0015$$

8-14

$$t > 0 \text{ 때}, i(t) = 0.5e^{-5000t}[A], v(t) = -25e^{-5000t}[V]$$

8-15

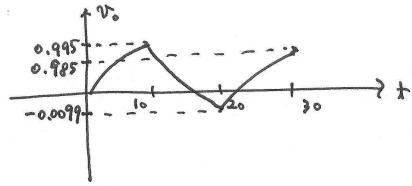
$$t > 0 \text{ 때}, v_C(t) = 20 [V]$$

8-16

$$0 < t < 10m \text{ 때}, v_o(t) = -100e^{-t} + 100$$

$$10m \leq t < 20m \text{ 때}, v_o(t) = 102.01e^{-t} - 100$$

$$20m \leq t < 30m \text{ 때}, v_o(t) = -102.03e^{-t} + 100, v_o(30m) = 0.985$$

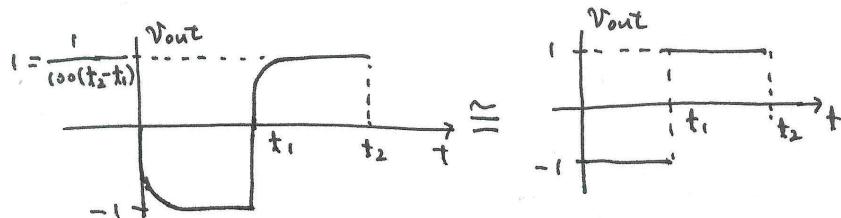


8-17

$$(a) \frac{dv_{out}}{dt} + 10^4 v_{out} = -10 \frac{dv_{in}}{dt}$$

$$(b) 0 < t < t_1 \text{ 때}, v_{out} = e^{-10^4 t} - 1$$

$$t_1 < t < t_2 \text{ 때}, v_{out} = 1 - e^{-10^4(t - 10m)}$$



## 제9장 RLC 회로의 완전응답

9-1

$$\omega_0 = \frac{1}{\sqrt{2}} \times 10^7 [rad/s]$$

9-2

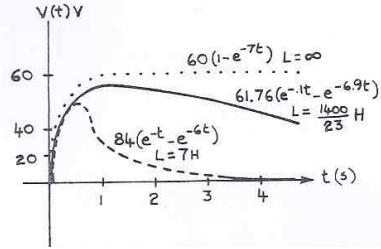
$$v_c(t) = \frac{3}{2}(e^{-t} - e^{-3t}) [V]$$

9-3

$$\frac{d^2v}{dt^2} + 7 \frac{dv}{dt} + 6v(t) = 0$$

(a)  $v(t) = 61.76(e^{-0.1t} - e^{-6.9t})$ ,  $v_{CMax}(0.622) = 57.2[V]$

(b)  $L = \infty$  면,  $v(t) = 60(1 - e^{-7t})$



9-4

$$i_L(0^+) = i_L(0^-) = 10[mA] , \text{ R의 값에 상관없으므로 } \frac{di(0^+)}{dt} = 0$$

9-5

$$\frac{d^2v}{dt^2} + \frac{1}{L[(1+b)R_2 + R_1]} \frac{dv}{dt} + \frac{1}{LC}v(t) = \frac{(1+b)R_2}{LC[(1+b)R_2 + R_1]} v_s$$

9-6

$$v(t) = 3e^{-3t} - e^{-t}$$

9-7

$$v(t) = -4e^{-2t} \sin 2t$$

9-8

$$v_C(t) = 0.25v_0e^{-0.293t} - 0.25v_0e^{-1.707t} - 0.354v_0te^{-1.707t}$$

9-9

$$v(t) = -0.77e^{43.32t} - 5.23e^{-3.32t} + 16$$

9-10

$$v(t) = 3e^{-400t} \cos 300t + 4e^{-400t} \sin 300t$$

9-11

(a)

$$\begin{bmatrix} \frac{di_1}{dt} \\ \frac{di_2}{dt} \\ \frac{dv_c}{dt} \end{bmatrix} = \begin{bmatrix} -4 & 0 & -2 \\ 0 & -4 & 2 \\ 1 & -1 & 0 \end{bmatrix} \begin{bmatrix} i_1 \\ i_2 \\ v_c \end{bmatrix} + \begin{bmatrix} 20 \\ 0 \\ 0 \end{bmatrix}$$

(b)  $i_2(t) = -1.5e^{-4t} - e^{-3t} - e^{-t} + 2.5, \quad v_1(t) = -3e^{-4t} - 2e^{-3t} - 2e^{-t} + 5 [V]$

9-12

$$i_1(t) = e^{-10^6 t} [9\cos(2 \times 10^6 t) - 3\sin(2 \times 10^6 t)] [mA]$$

9-13

$$i(t) = 16e^{-2000t} - 4e^{-8000t} + 24 [mA]$$

9-14

(a)  $v_1(t) = 132e^{-40t} + 1072e^{-160t} [mV]$

(b)  $v_2(t) = 400 - 264e^{-40t} - 536e^{-160t} [mV]$

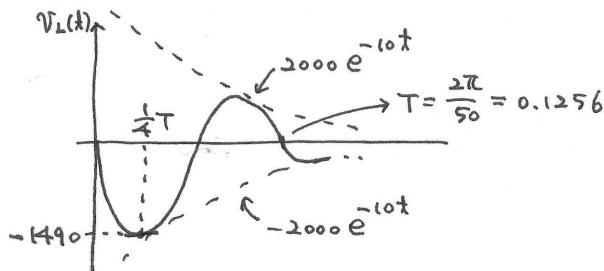
(c)  $v_3(t) = -528e^{-40t} - 268e^{-160t} + 400 [mV]$

9-15

$$v_C(t) = 250e^{-500t} - 125e^{-2000t} [V]$$

9-16

(a)  $v(t) = -2000e^{-10t} \sin 50t [V]$



(b) 최대값은 1/4 주기 값에서  $-1490 [V]$ .

9-17

$$\frac{d^3v_1(t)}{dt^3} + 2\frac{d^2v_1(t)}{dt^2} + 2\frac{dv_1(t)}{dt} + v_1(t) = \frac{I}{2}$$

(단,  $I$  는 상수이므로,  $\frac{d^2I}{dt^2} = 0, \frac{dI}{dt} = 0$  이다.)

## 제10장 정현파의 정상상태응답 해석

10-1

$$i(t) = 3.236 \cos(300t - 14.4^\circ)$$

10-2

(a)  $A = 8, b = -1$

(b)  $A = -20, a = -5\sqrt{3}$

10-3

(a)  $5 \angle 30^\circ$

(b)  $5\sqrt{2} + j5$

10-4

$$R = 4.53, L = \frac{2.115 \times 10^3}{2 \times 10^6} = 1.0575 \text{ [mH]}$$

10-5

$$i(t) = 0.5 + \frac{1}{6} \cos(4t + 45^\circ) [mA]$$

10-6

$$v_R = 5 \cos \omega t + \frac{5}{2} + 3 \sin \omega t = \sqrt{5^2 + 3^2} \cos(\omega t - \tan^{-1} \frac{5}{3}) + \frac{5}{2}$$

정현파의 실효값은 주파수와 상관없이  $v_{eff} = \frac{\sqrt{93}}{2}$

10-7

$$Y = 0.04 + 0.8j [\Omega], Z = \frac{1}{Y} = \frac{1}{0.04 + 0.8j}$$

10-8

$$i(t) = \frac{1}{\sqrt{2}} \cos 15^\circ e^{-1000t} \approx 0.683e^{-1000t}$$

10-9

$$i(t) = 1 \cos(t - 90^\circ)$$

10-10

$$v_c(t) = 5.74e^{-10(t-10)}$$

10-11

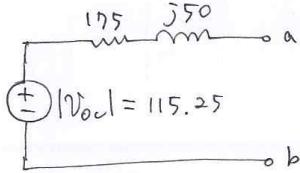
$$i(t) = 0.06364 \cos(20t - 2.07^\circ) [A]$$

10-12

$$i(t) = 5e^{-\frac{1}{50}t}$$

10-13

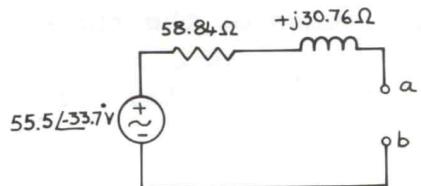
$$Z_{th} = 175 + j50, \quad V_{oc} = 115.25 [V]$$



10-14

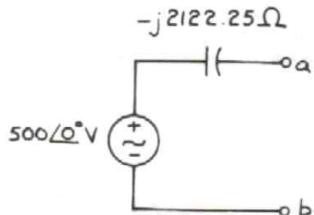
$$Z_{th} = 53.84 + j30.76$$

$$V_{oc} = V_{th} = 55.5 \angle -33.7^\circ$$



10-15

$$Z_{th} = -j2122.25 \Omega, \quad V_{oc} = 500 \angle 0^\circ$$



노턴 등가회로는 다음과 같다.

$$\vec{I} = \frac{500}{-j2122.25} A \quad \text{Ampere}$$

$$\vec{I} = 0.236 / 90^\circ A.$$

10-16

$$v_{Cs} = \frac{1}{2} \sin t - \frac{1}{2} \cos t$$

순간응답  $v_{ct} = \frac{1}{2} e^{-t}$ , 이는  $t = \infty$  때, 정상상태에서 0으로 수렴함으로, 위의 수식의 정상 상태응답이 맞는 것을 알 수 있다.

10-17

$$I_1 = -3 + 0.890 \cos(250t - 57.7^\circ), \quad V_2 = 75 + 13.3 \cos(250t - 57.7^\circ)$$

10-18

$$v(t) = 2\cos t + 2\sin t - 23e^{-2t} + 26e^{-3t}$$

10-19

$$i_L(t) = i_{L1}(t) + i_{L2}(t) = \frac{1}{2\sqrt{2}} \sin(t - 45^\circ) + \frac{11}{12} e^{-\frac{2}{3}t} + \frac{1}{3}$$

10-20

$$v_1(t) = 1,70e^{-5t} + 12.78e^{-2t} - 15e^{-3t}$$

## 제11장 교류 정상상태 전력

11-1

$$R = 10\Omega, C = 0.1F$$

11-2

(a)  $V_1 = 528 \angle 15.83^\circ$

(b) 소자는 커패시터 소자,  $C = 426\mu F$

11-3

$$P = 573.11 [W]$$

11-4

$$C = 0.1\mu F$$

11-5

전체 전력소모량은  $13.92[W]$

11-6

(a)  $V_{SS} = 736 \angle -3^\circ [V]$

(b) 전송효율 =  $89.7[\%]$

11-7

$$P_{AV} = 63.7 [W]$$

11-8

$R = 400\Omega$ , 전류  $|I| = 2.18[A]$ ,  $X = \pm 34.4\Omega$  즉,  $X$  가 인덕터라면, + 측, 커패시터라면 - 측

11-9

R-C 가지 소모 전력  $P = VI\cos\theta = 707.4[W]$ , R-L 가지 소모 전력  $P = 1989[W]$

11-10

$$P(t) = 400\cos(6t + 20.60^\circ)$$

11-11

$$I_1 = 2[A], V_1 = 8 - j6[V], V_2 = 40 - j30[V], I_2 = 0.4[A]$$

11-12

$$P_{2\Omega} = 35.8621[mA], P_{source} = 52.41[mW]$$

11-13

$$Z_T = 6.98 - j10.38$$

11-14

$$\begin{aligned} v &= R_1 i_1 + (L_1 + L_2) \frac{di_1}{dt} + M \frac{di_2}{dt}, \\ 0 &= L_3 \frac{d^2 i_2}{dt^2} + M \frac{d^2 i_2}{dt^2} + R_2 \frac{di_2}{dt} + \frac{1}{C_1} i_2 \end{aligned}$$

11-15

(a)  $I_1 = 176 \angle -25.16^\circ = 159.30 - j74.83$

(b)  $\frac{V_1}{I_1} = Z_1 = 0.463 + j0.231 = 0.517 \angle 26.52^\circ$

11-16

$$Z_{ab} = \frac{3s^4 + 12s^3 + 19s^2 + 15s + 4}{5s^3 + 11s^2 + 4s} \quad \text{단, } s = j\omega$$

11-17

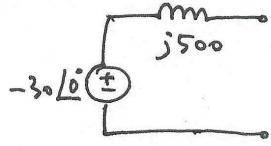
$$i_R(t) = 1.79\cos(5000t + 26.6^\circ)[mA]$$

11-18

$$i_2(t) = 0.435(e^{-0.73t} - e^{-0.27t})u(t)$$

11-19

(a)  $Z_{th} = j500[\Omega]$ ,  $V_{oc} = -30 \angle 0^\circ$



(b)  $Z_L = Z_{th}^* = -j500$

(c) 부하를 가하기 전 역률은 0

## 제12장 3상 회로

12-1

$$I_{aA} = \frac{V_{an}}{Z} = \frac{390 \angle 30^\circ}{319.4 \angle -90^\circ} = 1.22 \angle 120^\circ, I_{bB} = 1.22 \angle 0^\circ, I_{cC} = 1.22 \angle -120^\circ$$

12-2

$$I_{nn'} = I_{11'} + I_{22'} + I_{33'} = 22.9 \angle -18.8^\circ$$

12-3

$I_{nn'} = I_{an} + I_{bn} + I_{cn}$ , 모두 합하면, 균형 3상의 경우 0 이 된다.

12-4

$I_{nn'} = I_{an} + I_{bn} + I_{cn}$ , 모두 합하면, 균형 3상의 경우 0 이 된다.

12-5

(a)  $P_{\text{Total}} = 3 \times 1440 = 4.32[\text{KW}]$

(b)  $P_{\text{Total}} = 3 \times 1920 = 5.76[\text{KW}]$

(c)  $P_{\text{송전선로}} = |I|^2(0.2) = 472.8[W]$ , 전 전력은 3배인 1.42[KW].

12-6

$$P_A = I_{aA}^* I_{aA} Z_A = 16.88 + j12.71, 3P_A = 50.64[W]$$

12-7

(b) 직렬 연결된 부하의 전체 평균전력은,  $P_1 + P_2 = 6 + 5.81 = 11.81\text{KW}$

전체 리액턴스전력  $P_{x1} + P_{x2} = 8 - 4.36 = 3.64\text{Kvar}$  가 된다.

(a) 전체 피상전력  $P_A = 12.36[\text{Kva}]$

(c) 선전류  $I_L = 32.4[A]$

(d) 역률  $pf = 0.955$ (뒤진역률)

12-8

$$C = \frac{1}{47 \times 377} = 56.5 \mu F$$

12-9

$$C = \frac{1}{141 \times 377} = 18.8 [\mu F]$$

12-10

(a)  $|i_{Aa}| = 160.5 [A]$

(b)  $|v_{AB}| = \sqrt{3} \times 751.88 = 1302.3$

(c) 역률 =  $\cos(\angle v_{An} - \angle I_{An}) = 0.42$  (뒤진역률)

12-11

(a)  $v_{cn} = 390 \angle (-90^\circ - 120^\circ) = 390 \angle -210^\circ$

(b)  $v_{bc} = v_{bn} - v_{cn} = 675 \angle -60^\circ$

(c)  $v_{ac} = v_{an} - v_{cn} = 675 \angle 0^\circ$

12-12

(a) 조명부하에 의한 전력소모  $P_1 = 12.9 [KW]$ , 전체평균전력소모  $P = 3P_1 = 38.7 [KW]$

(b) 모터에 의한 평균전력소모  $P_2 = 15.46 [KW]$ , 전체평균전력소모  $P = 3P_2 = 46.38 [KW]$

12-13

$$|I_a| = |I_b| = |I_c| = 13.85 [A]$$

12-14

$$I_{aa'} = I_1 = 3.66 \angle 15^\circ, I_{cc'} = -I_2 = 11.96 \angle 66^\circ, I_{bb'} = -I_{aa'} + I_{cc'} = 14.54 \angle -125.1^\circ [A]$$

12-15

$$v_{a'b'} = v_{a'n'} + v_{n'b'} = 1509 \angle 20.6^\circ, v_{b'c'} = v_{b'n'} + v_{n'c'} = 1392 \angle -99.0^\circ,$$

$$v_{c'a'} = v_{c'n'} + v_{n'a'} = 1461 \angle 144.8^\circ$$

12-16

(a)  $|I_1| = 3.273 [A]_s$

(b)  $|I_2| = 6.288 [A]_s$

(c)  $|I_{phase}| = 8 [A]_{rms}$

12-17

$$P_P = 2912, \text{ 전체평균전력 } P = 3 \times 2912 = 8736 [W]$$

12-18

$$\text{선전류는, } I_{aA} = 9 \angle 97.4^\circ [A]_s, I_{bB} = 9 \angle -22.6^\circ [A]_s, I_{cC} = 9 \angle -142.6^\circ [A]_s$$

12-19

$$|I| = 10\sqrt{3} [\text{A}]$$

12-20

$$(a) I_{P1} = 5.2 \angle 0^\circ, I_{P2} = 10.4 \angle 180^\circ, I_{P3} = 13.8 \angle 195^\circ$$

$$(b) \text{ 선전류 } I_{L1} = 18.5 + j3.57[A], I_{L2} = -15.6 + j0[A], I_{L3} = -2.9 - j3.57[A]$$

$$(c) \text{ 선간전압 } V_{AB} = 390\sqrt{3} \angle 60^\circ [V]_s, V_{BC} = 390\sqrt{3} \angle -60^\circ [V]_s,$$

$$V_{CA} = 390\sqrt{3} \angle 180^\circ [V]_{\text{rms}}$$

## 제13장 라플라스 변환 회로해석

13-1

$$A\left(\frac{1}{s} - \frac{1}{s-b}\right)$$

13-2

$$\mathcal{L}(f(t)) = -\frac{5}{3s^2} + \frac{5}{s} + e^{-\frac{21}{5}s} \left(\frac{5}{3s^2}\right)$$

13-3

$$f(t) = (3 - 4e^{-t} + e^{-2t})u(t)$$

13-4

$$(a) f(t) = [e^{-t} - e^{-t}\cos(st) + e^{-t}\sin(2t)]u(t)$$

$$(b) f(t) = [2te^{-t} - e^{-t} + e^{2t}]u(t)$$

13-5

$$F(s) = \frac{3(1 - e^{-2s})}{s}$$

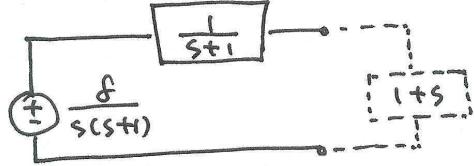
13-6

$$i(t) = (1 - e^{-t})u(t)$$

13-7

$$(a) \quad V_{oc}(s) = \frac{8}{s(s+1)}$$

$$Z_{th} = Z_{ab}(s) = \frac{1}{s+1}$$



$$(b) \quad v_{ab}(t) = 4 - 4e^{-t} \cos t + 4e^{-t} \sin t = 4 + 4\sqrt{2} e^{-t} \cos(t - 135^\circ)$$

13-8

$$\begin{aligned} v(t) &= 1.365e^{-6.571t} + 0.636e^{-0.715t} \cos 0.314t - 1.85e^{-0.715t} \sin 0.314t \\ &= 1.365e^{-6.571t} + 1.956e^{-0.715t} \cos(0.314t - 23.7^\circ) \end{aligned}$$

13-9

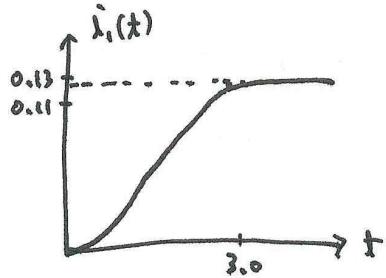
$$\mathcal{L}^{-1}(V_c(s)) = v_c(t) = 10000e^{-5t}u(t)$$

13-10

$$I_x(t) = \left( \frac{5}{12}t - \frac{25}{18} + \frac{95}{36}e^{-\frac{3}{4}t} \right) u(t)$$

13-11

$$I_1(t) = \frac{1}{8} - \frac{1}{8}e^{-4t} - \frac{1}{2}te^{-2t}$$



13-12

$$V_c(s) = \frac{3s + 18 + 3V_x(s)}{s^2 + 6s + 8}$$

13-13

$$f(t) = \sum_{n \text{ odd}}^{\infty} \frac{8V}{n^2\pi^2} \cos n\omega t = \frac{8V}{\pi^2} [\cos \omega t + \frac{1}{9} \cos 3\omega t + \frac{1}{25} \cos 5\omega t + \dots]$$

13-14

$$f(t) = \frac{\pi^2}{3} + \sum_{n=1}^{\infty} [(-1)^n \frac{4}{n^2} \cos(nt)]$$

13-15

처음 4항으로 근사한 式에 급수는

$$f(t) = \frac{8\sqrt{2}}{\pi^2} [\sin(\frac{\pi t}{4}) + \frac{1}{9}(\frac{3\pi t}{4}) - \frac{1}{25}\sin(\frac{5\pi t}{4}) - \frac{1}{49}\sin(\frac{7\pi t}{4})], f(2) = 0.9965$$

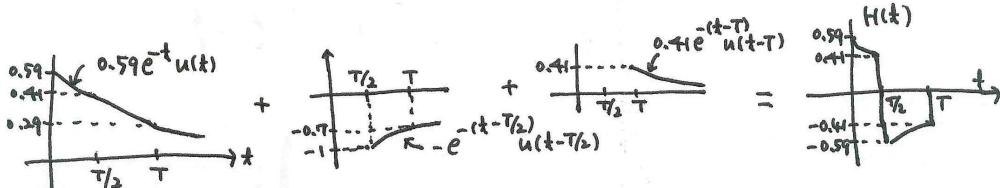
13-16

$$(a) \mathcal{L}^{-1}(H(s)) = h(t) = \frac{1}{3} [e^{-\frac{5}{12}t} \cos \frac{\sqrt{23}}{12}t + e^{-\frac{5}{12}t} \sin \frac{\sqrt{23}}{12}t] \\ = \frac{\sqrt{2}}{3} e^{-0.417t} \sin(0.4t + 45^\circ)$$

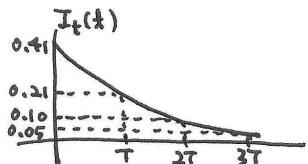
$$(b) H(s) = \frac{2s+1}{6s^2+5s+2}$$

13-17

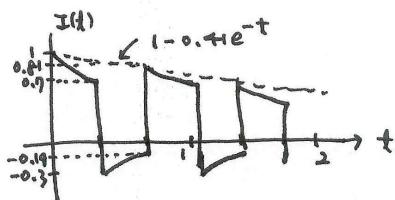
$$H(t) = 0.59e^{-t}u(t) - e^{-(t-0.35)}u(t-0.35) + 0.41e^{-(t-0.69)}u(t-0.69)$$



$$I_t(t) = 0.41e^{-t}$$



$$I(t) = I_t(t) + I_p(t)$$



## 제14장 2-포트 회로망

14-1

$$y_{21} = \frac{I_2}{V_1} \Big|_{V_2=0} = -\frac{1}{14}, \quad y_{12} = \frac{I_1}{V_2} \Big|_{V_1=0} = -\frac{1}{14}, \quad y_{22} = \frac{I_2}{V_2} \Big|_{V_1=0} = \frac{5}{14}\mathcal{U},$$

$$y_{11} = \frac{I_1}{V_1} \Big|_{V_2=0} = \frac{3}{14}, \quad Y = \begin{bmatrix} \frac{3}{14} & -\frac{1}{14} \\ -\frac{1}{14} & \frac{5}{14} \end{bmatrix}$$

14-2

$$y_{11} = \frac{I_1}{V_1} = \frac{1}{R_1} + \frac{1+k}{R_2}, \quad y_{21} = \frac{-I_{R_2}}{V_1} = -\frac{1+k}{R_2},$$

$$y_{12} = \frac{I_1}{V_2} \Big|_{V_1=0} = -\frac{1}{R_2}, \quad y_{22} = \frac{I_2}{V_2} = \frac{1}{R_2} + \frac{1}{R_3}$$

14-3

$$h_{12} = \frac{V_1}{V_2} \Big|_{I_1=0} = \frac{Z_3}{Z_2+Z_3}, \quad h_{22} = \frac{I_2}{V_2} \Big|_{I_1=0} = \frac{1}{Z_2+Z_3}$$

$$h_{11} = \frac{V_1}{I_1} = Z_1 + \frac{Z_2Z_3}{Z_2+Z_3}, \quad h_{21} = \frac{I_2}{I_1} \Big|_{V_2=0} = -\frac{Z_2}{Z_2+Z_3}$$

14-4

$$z_{11} = \frac{y_{22}}{|Y|} = \frac{y_{22}}{y_{11}y_{22} - y_{12}y_{21}} = 4.44\Omega, \quad z_{12} = z_{21} = \frac{-y_{12}}{|Y|} = 2.22\Omega, \quad z_{22} = \frac{y_{11}}{|Y|} = 11.11\Omega$$

14-5

$$z_{11} = \frac{s+1}{s(s+2)} + \frac{s}{2} = z_{22}, \quad z_{12} = z_{21} = \frac{s+1}{s(s+2)} + \frac{s}{2} - \frac{1}{s+1} = z_{21}$$

14-6

$$y_{11} = \frac{s^2+2s}{s+1}, \quad y_{12} = -\frac{s}{s+1} = y_{21}, \quad y_{22} = \frac{3s^3+3s+1}{s(s+1)}$$

$$Z = Y^{-1} \text{ } \circ \text{므로, } z_{11} = \frac{y_{22}}{|Y|} = \frac{3s^2+3s+1}{s(3s^2+5s+2)}, \quad z_{12} = z_{21} = \frac{-y_{12}}{|Y|} = \frac{s}{3s^2+5s+2},$$

$$z_{22} = \frac{y_{11}}{|Y|} = \frac{s^2+2s}{3s^2+5s+2}$$

14-7

$$h_{12} = \frac{V_1}{V_2} \Big|_{I_1=0} = \frac{r_b}{r_b+r_c} \approx 1.6 \times 10^{-3}, \quad h_{22} = \frac{I_2}{V_2} \Big|_{I_1=0} = \frac{1}{r_b+r_c} \approx 2 \times 10^{-6}\mathcal{U}.$$

$$h_{21} = \frac{I_2}{I_1}|_{V_2=0} = -\left[\frac{\alpha r_c + r_b}{r_b + r_c}\right] \approx -0.981$$

14-8

$$h_{11}(s) = \frac{2s^2 + 1}{s(s^2 + 1)}, \quad h_{12}(s) = \frac{s^2}{s^2 + 1}, \quad h_{21}(s) = \frac{-s^2}{s^2 + 1}, \quad h_{22}(s) = \frac{s}{s^2 + 1}$$

14-9

$$h_{11} = \frac{Z_1 Z_2}{Z_1 + Z_2}, \quad h_{22} = \frac{Z_1 + (Z_2 + Z_3)}{(Z_1 + Z_2) Z_3}, \quad h_{12} = \frac{Z_1}{Z_1 + Z_2}, \quad h_{21} = -\frac{Z_1}{Z_1 + Z_2}$$

14-10

$$(a) \quad Z_{11} = Z_{22} = 1 + \frac{1}{s} = \frac{s+1}{s}, \quad y_{11} = y_{22} = \frac{s+1}{s+1+1} = \frac{s+1}{s+2}$$

$$Z_{12} = Z_{21} = \frac{1}{s}, \quad y_{12} = -\frac{1}{s+2} = y_{21}$$

$$(b) \quad Z_{11} = Z_{22} = \frac{s+1}{s}, \quad y_{11} = y_{22} = \frac{s+1}{s+2}, \quad Z_{12} = -\frac{1}{s}, \quad y_{12} = y_{21} = \frac{1}{s+2}$$

14-11

$$A = \frac{V_2}{V_1} = \frac{Z_a Z_3 + Z_a Z_1 + \Delta Z}{Z_a Z_3 + \Delta Z} \quad \text{and}, \quad \Delta Z = Z_1 Z_2 + Z_2 Z_3 + Z_1 Z_3$$

$$C = \frac{Z_1 + Z_a + Z_2}{Z_a Z_3 + \Delta Z}, \quad B = \frac{Z_a \Delta Z}{Z_a Z_3 + \Delta Z}, \quad D = \frac{Z_a (Z_2 + Z_3) + \Delta Z}{Z_a Z_3 + \Delta Z}$$

14-12

$$y_{11} = \frac{Z_2 + Z_3}{\Delta Z}, \quad y_{22} = \frac{Z_1 + Z_2}{\Delta Z}, \quad y_{12} = y_{21} = -\frac{Z_2}{\Delta Z}$$

14-13

$$h_{11} = 2\mathcal{U}, \quad h_{21} = -0.8, \quad h_{12} = 0.8, \quad h_{22} = 0.28\mathcal{U}$$

14-14

$$y_{11} = G_1 + G_3, \quad y_{12} = y_{21} = -G_3, \quad y_{22} = G_2 + G_3$$

$$Y = Y_1 + Y_2 = \begin{bmatrix} Cs + \frac{1}{Ls} + G_1 + G_3 & -(Cs + G_3) \\ -(Cs + G_3) & Cs + \frac{1}{Ls} + G_2 + G_3 \end{bmatrix}$$

14-15

$$Z = Z_1 + Z_2 = \begin{bmatrix} 2(sL + \frac{1}{Cs}) & sL + \frac{1}{Cs} \\ sL + \frac{1}{Cs} & 2(sL + \frac{1}{Cs}) \end{bmatrix}$$

14-16

$$z_{11} = \frac{1}{sC} + R + sL_1, \quad z_{22} = R + s(L + L_2), \quad z_{12} = sM = z_{21}$$

14-17

$$\frac{V_L}{V_1} = 90000$$

14-18

$$Z = \begin{bmatrix} R_1 + R_3 + s(L_1 + L_3 + 2M_1) & R_3 + s(L_3 - M_2 + M_1) \\ R_3 + s(L_3 - M_2 + M_1) & R_2 + R_3 + s(L_2 + L_3) \end{bmatrix}$$

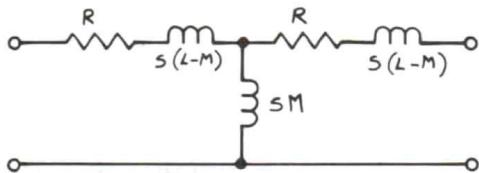
14-19

$$z_{12} = \frac{V_1}{I_2} \Big|_{I_1=0} = \frac{Z_1 Z_2}{Z_a + Z_1 + Z_2} + Z_3, \quad z_{22} = Z_2 - \frac{Z_2^2}{Z_a + Z_1 + Z_2} + Z_3,$$

$$z_{11} = Z_1 + Z_3 - \frac{Z_1^2}{Z_a + Z_2 + Z_1}, \quad z_{21} = \frac{V_2}{I_1} = \frac{Z_1 Z_2}{Z_a + Z_2 + Z_1} + Z_3 = z_{12}$$

14-20

$$Z_1 = R + s(L - M), \quad Z_2 = sM, \quad Z_3 = R + s(L - M)$$



$$Z_5 = \frac{2RL}{M} + \frac{1}{s} \frac{R^2}{M} + s \left( \frac{L^2}{M} - M \right)$$

$$Z_4 = R + s(L + M) = Z_6$$

등가  $\Pi$  형 회로는

